



RF Ranging with LoRa Leveraging RTL-SDRs and GNU Radio

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Exploring COTS, LoRa, GNU Radio, and RF Ranging

COTS Internet-of-Things (IoT) transceiver technology provides a useful set of features for RF aided complementary Positioning, Navigation, and Timing (PNT)

- Long Range: More than 10km
- Low Cost: IoT transceivers are inexpensive
- Low Power Consumption: IoT transceivers can operate for many years
- Majority of modules lack access to PHY for supporting PNT

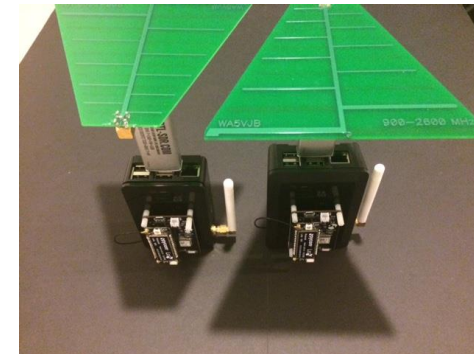


Leverage GNU Radio to prototype a LoRa RF ranging Python block without requiring access to physical layer measurements from the IoT transceiver



Leverage this LoRa RF ranging block as part of a low cost experimental RF ranging system based on IoT transceiver technology with low SWAP-C SDRs

- PNT Sub-GHz Software Defined Radio (PUGS)



Low Cost SDRs and IoT RF Modules

RTL-SDR:

- Extremely Inexpensive
- Tuning: 500 kHz up to 1.75 GHz
- 1PPM TCXO
- Max sampling rate is 2.4 Msps
- ENOB is ~7 bits
- USB Interface



Pluto SDR:

- Inexpensive
- Tuning: 300 MHz up to 3.8 GHz
- Bandwidth: 200kHz to 20 MHz
- Max sampling rate is 61.44 Msps
- 12-bit bit DACs and ADCs
- USB Interface



LoRa Sub-GHz Modules:

- Inexpensive
- 433 MHz, 868 MHz, and 915 MHz
- Bandwidths: 125 kHz, 250 kHz, and 500 kHz
- 157 dB maximum link budget
- +14 dBm high efficiency PA



LoRa 2.4 GHz Modules :

- Inexpensive
- Ranging Engine, Time-of-flight function
- Bandwidths: 125 kHz, 250 kHz, 500 kHz, and 1.6 MHz
- +12.5 dBm high efficiency PA



Components of PNT Sub-GHz SDR (PUGS)

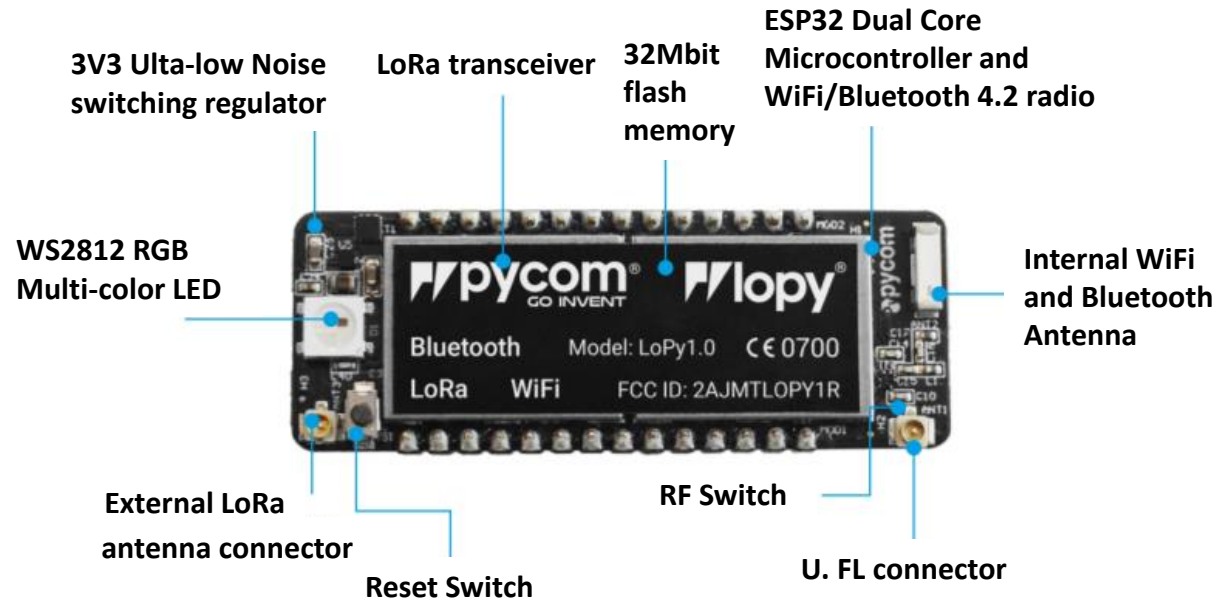


Image courtesy of

<https://docs.pycom.io/chapter/datasheets/downloads/lopy-specsheet.pdf>

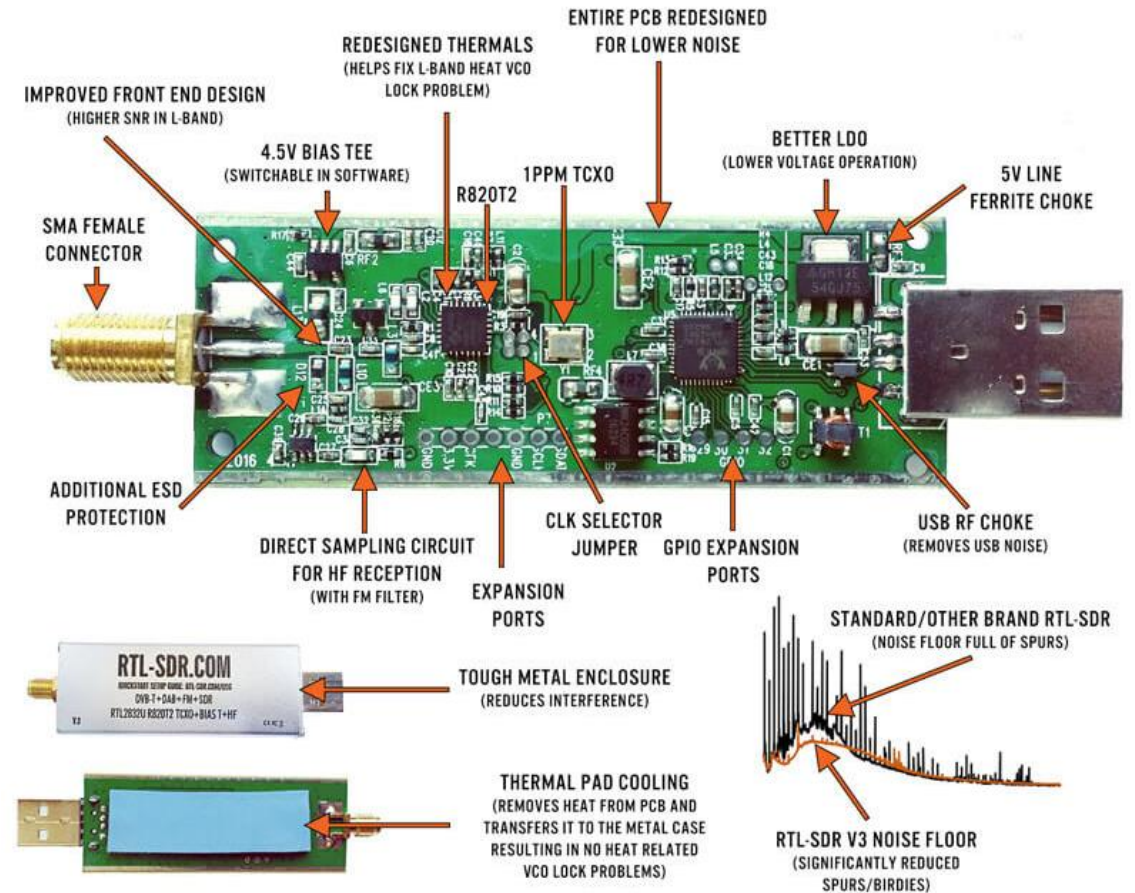


Image courtesy of <https://www.rtl-sdr.com/buy-rtl-sdr-dvb-t-dongles/>

Components of PNT Sub-GHz SDR (PUGS)

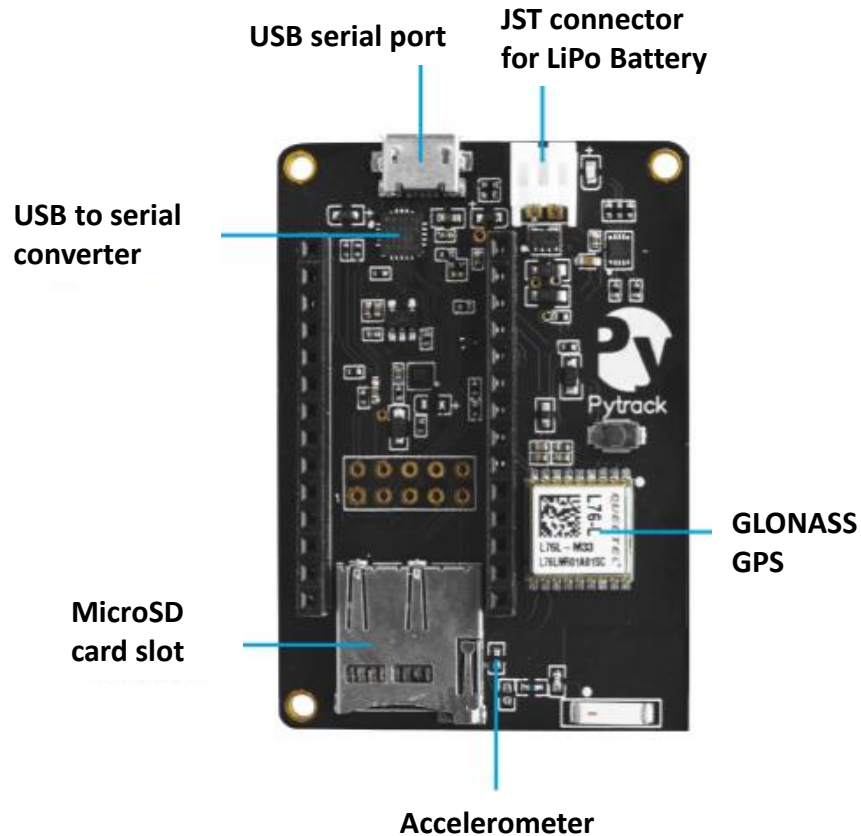


Image courtesy of <https://pycom.io/wp-content/uploads/2017/08/pytrackSpecsheetAugust2017n.pdf>

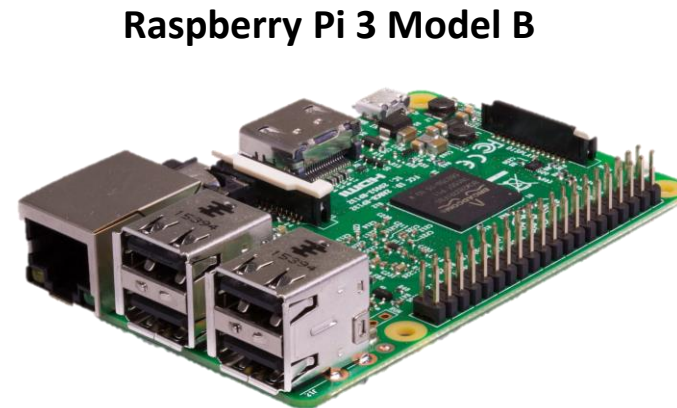
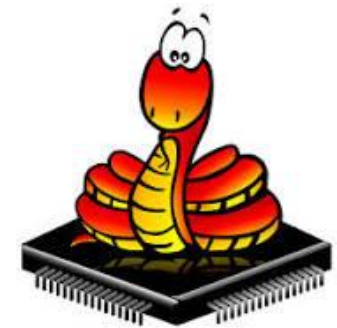


Image courtesy of <https://www.raspberrypi.org/products/raspberry-pi-3-model-b/>

Micropython

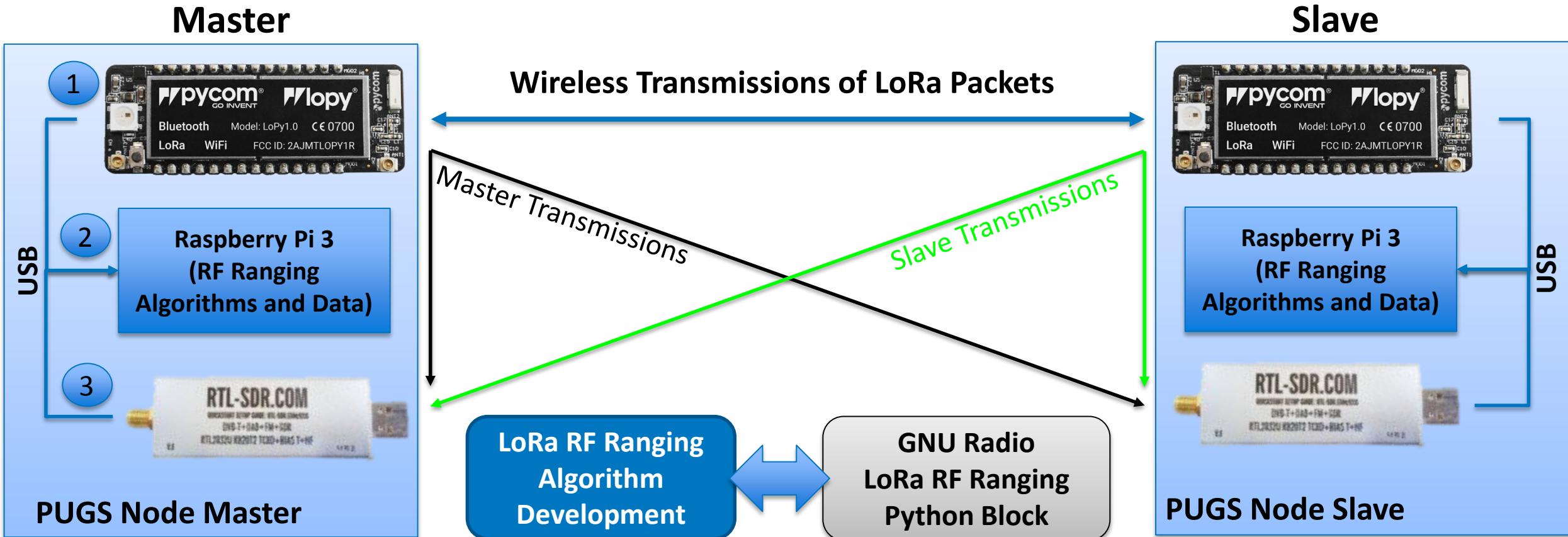


Python



Images courtesy of <https://commons.wikimedia.org>

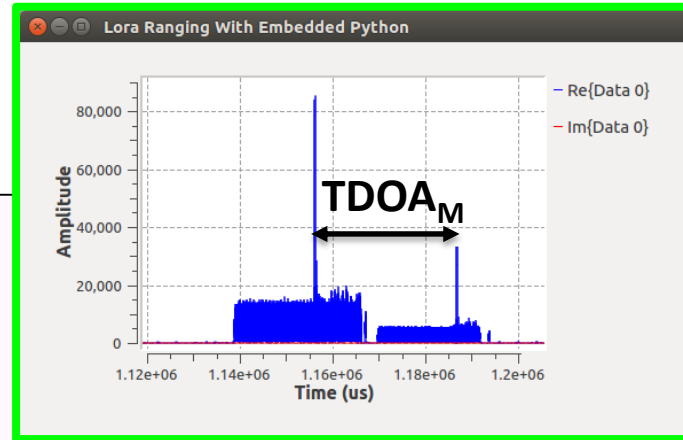
Low SWAP-C Hybrid RF Ranging SDRs



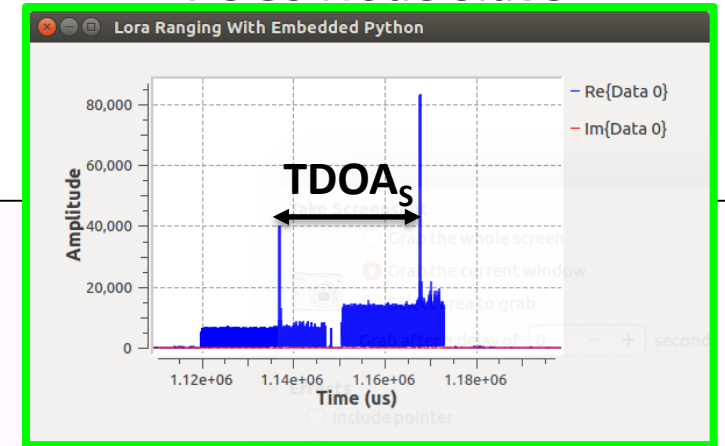
PUGS Hybrid (Active/Passive) RF Ranging Setup based on LoRa Transceiver Technology

GNU Radio Embedded Python Flow Graph

PUGS Node Master



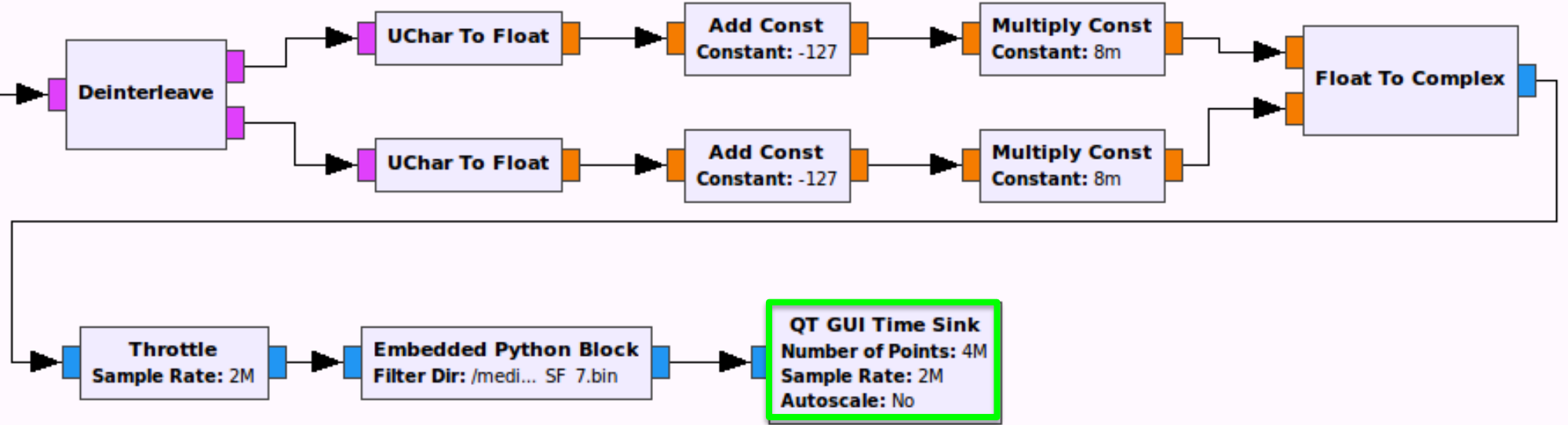
PUGS Node Slave



Options
 ID: Embedded ... Lora_Ranging
 Generate Options: QT GUI

Variable
 ID: samp_rate
 Value: 2M

File Source
 File: ...ster_903000000_1.bin
 Repeat: No



Components of PNT Sub-GHz SDR (PUGS)

Features of PUGS

- RF Ranging protocols written in Micropython
- Python based I/Q data capture scripts on RPI 3
- RTL-SDR for LoRa Packet Capture
- GNU Radio Installation with a modified gr-lora OOT

Pycom IoT Transceiver

- WiFi
- Bluetooth
- LoRa

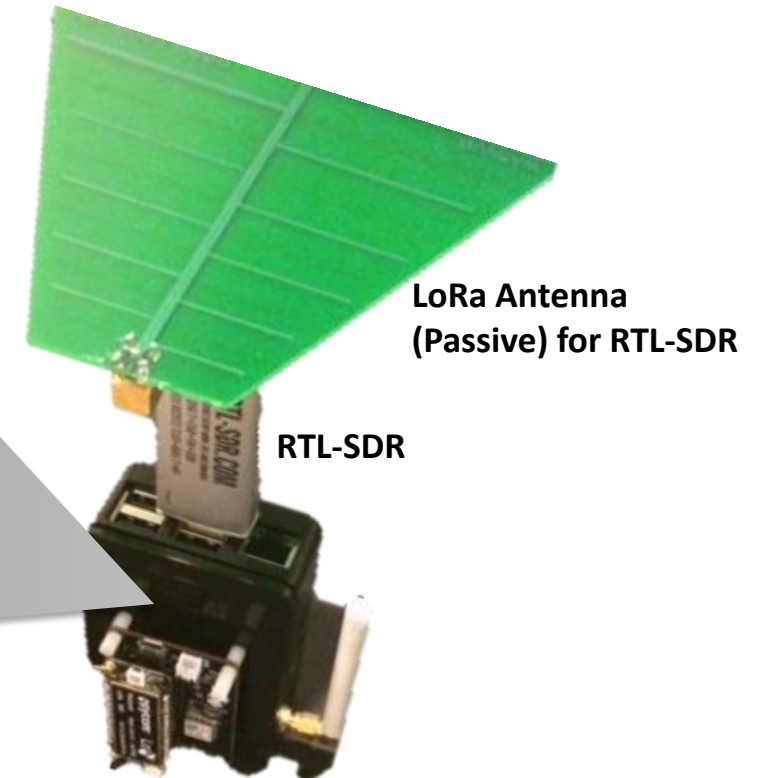
Raspberry Pi 3 (RPI 3)

Pycom IoT Pytrack Board

- Multi-GNSS Receiver
- Accelerometer
- USB interface for RPI3

GNSS Receiver

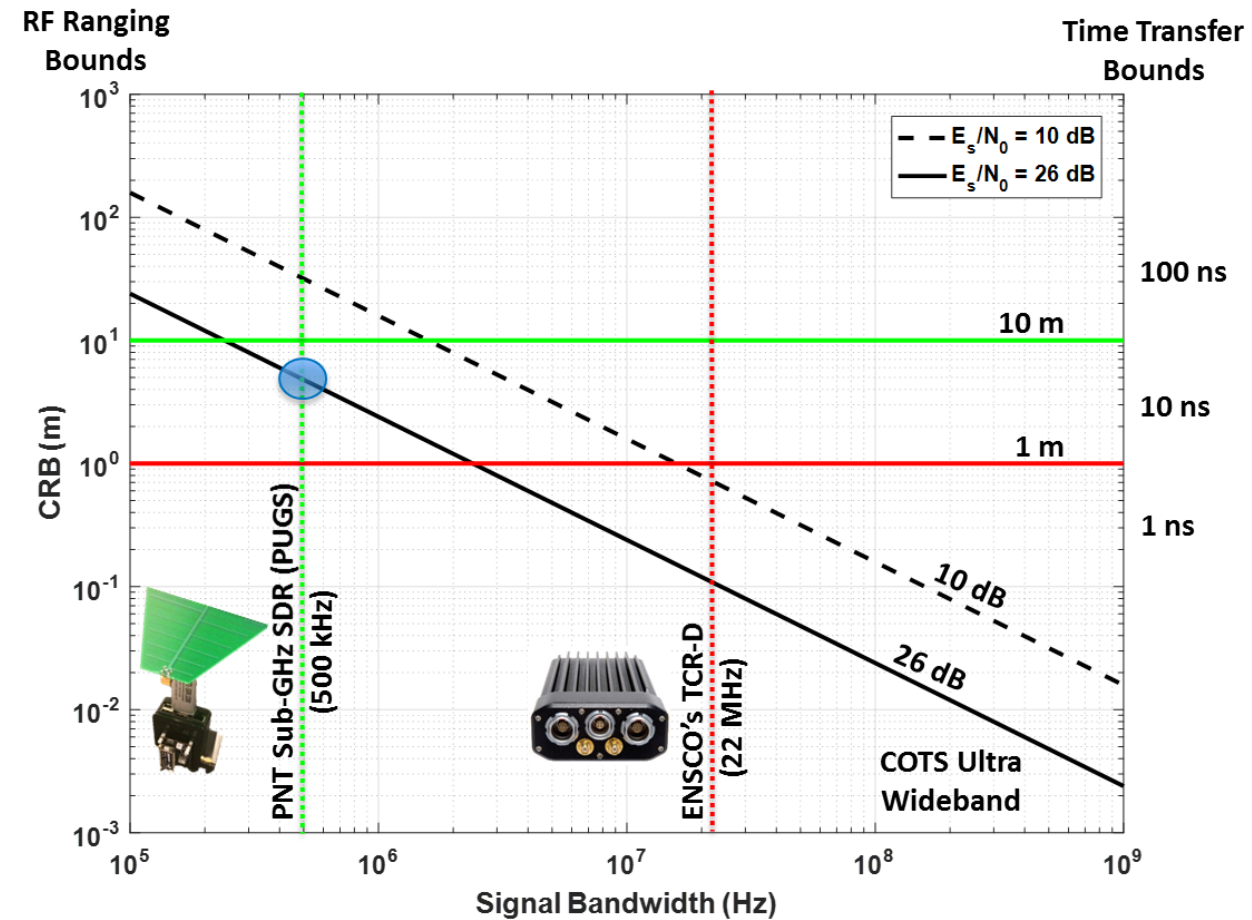
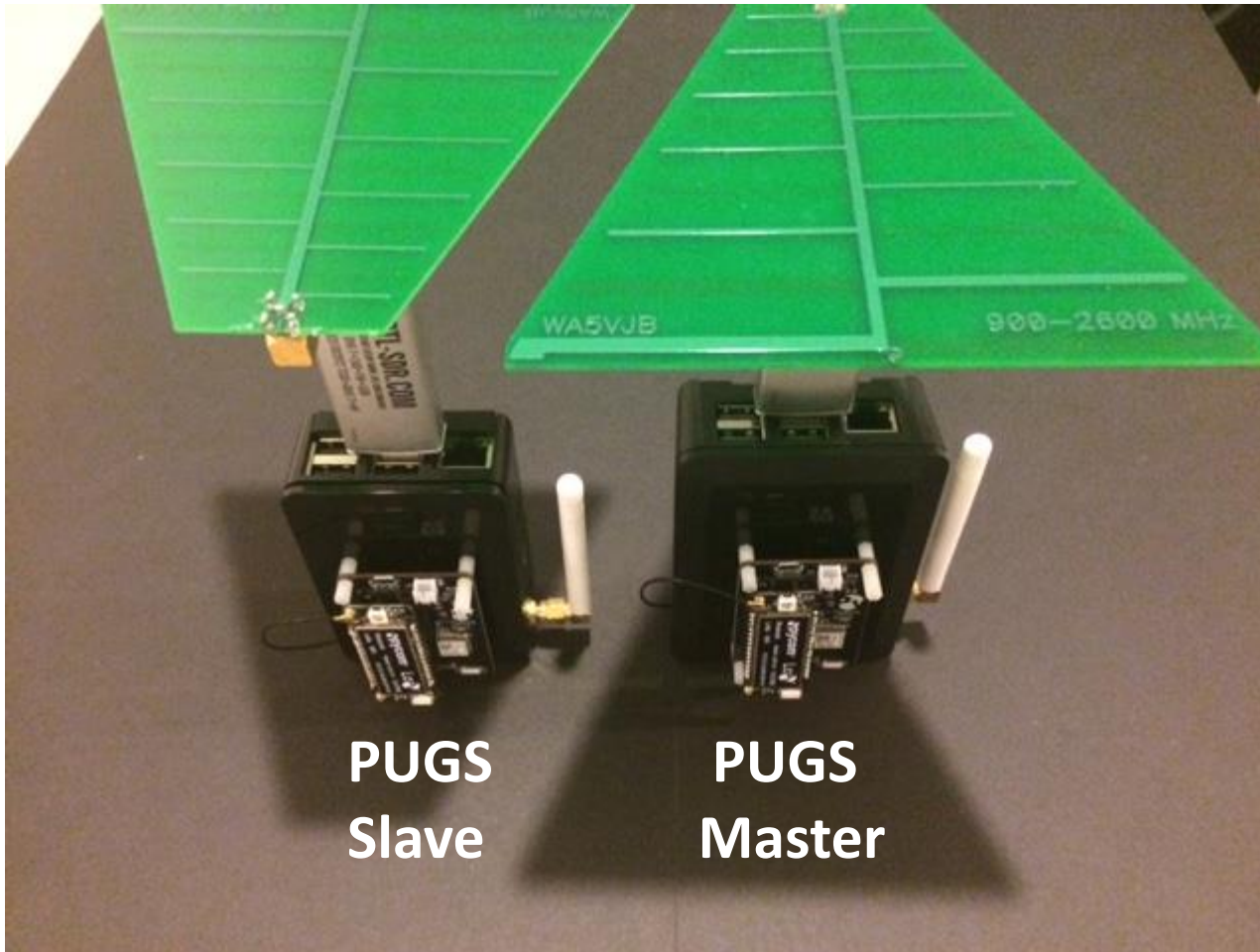
LoRa TX/RX Antenna



LoRa Antenna (Passive) for RTL-SDR

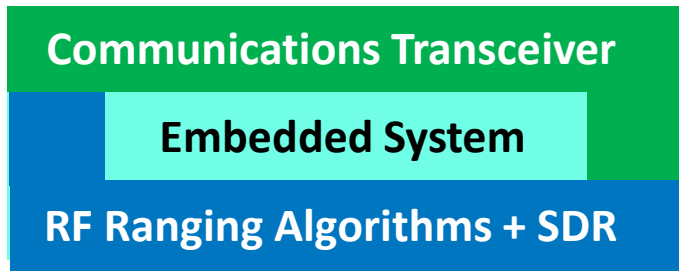
RTL-SDR

Exploring RF Ranging and Time Transfer with PUGS



Decoupling RF Ranging Algorithms for COTS

ENSCO's Timing, Communications, and Ranging Device (TCR-D)



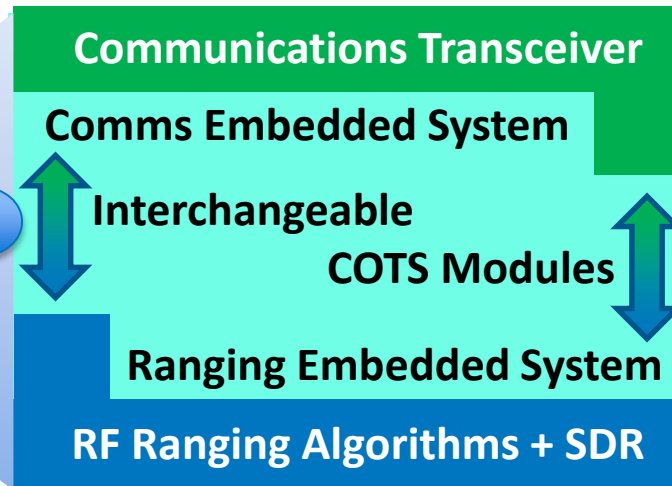
“Assured PNT with a Cell Phone IMU and Carrier Phase RF Measurements for GNSS Denied Environments” (JNC 2018)

“Wireless Synchronization Approach to Create Distributed Coherent Phased Arrays” (JNC 2018)

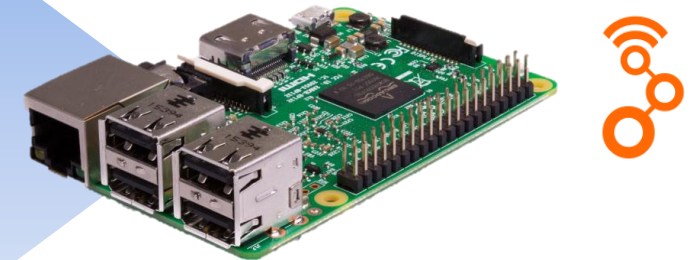
1



2



One example of a Sub-GHz COTS Communications Transceiver for PUGS Narrowband RF Ranging (BW = 500 kHz)



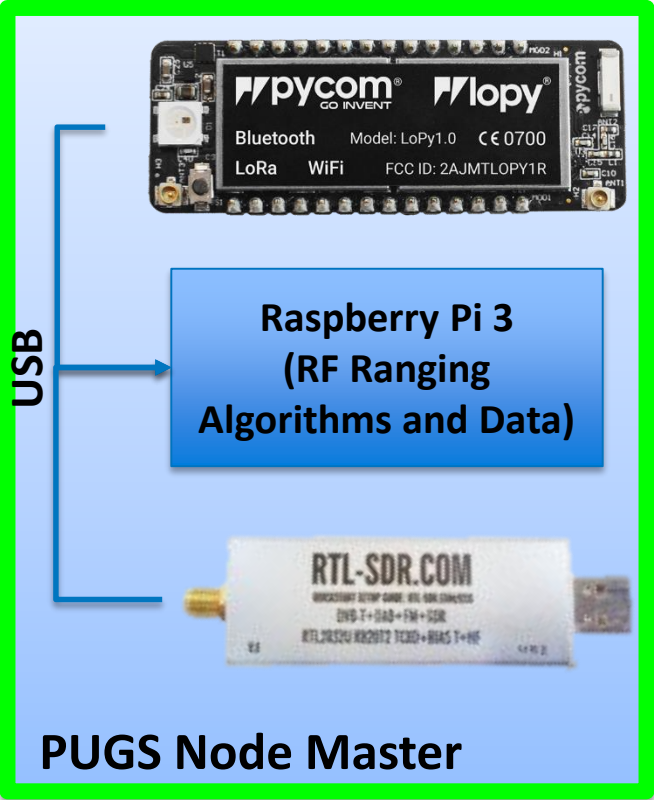
3



One example of a receive only SDR for Narrowband Sampling ($F_s = 2\text{MSPs}$)

Experimental Operation with PUGS

Master

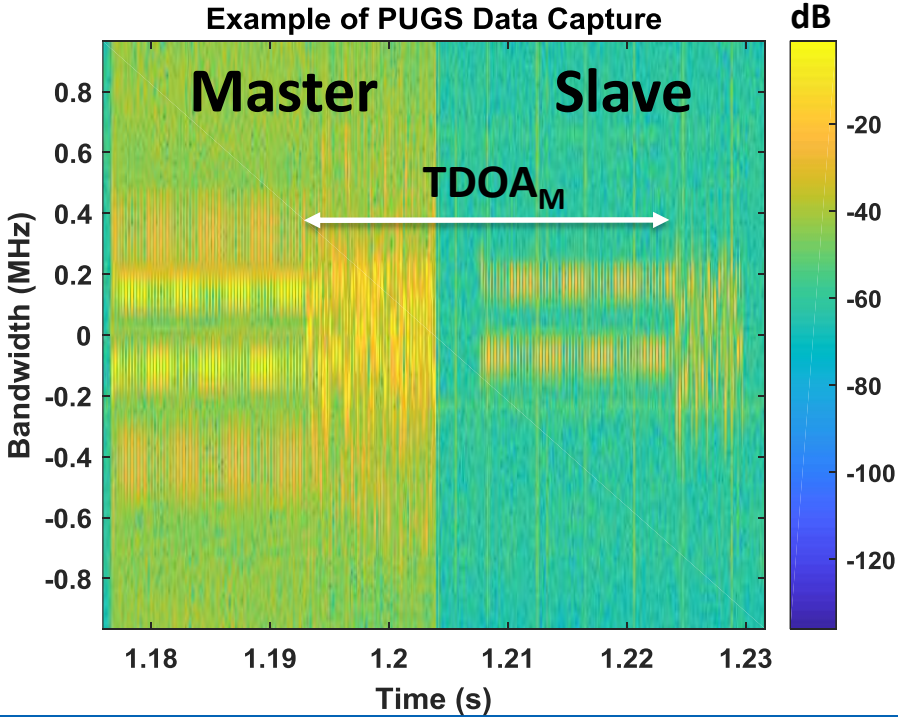
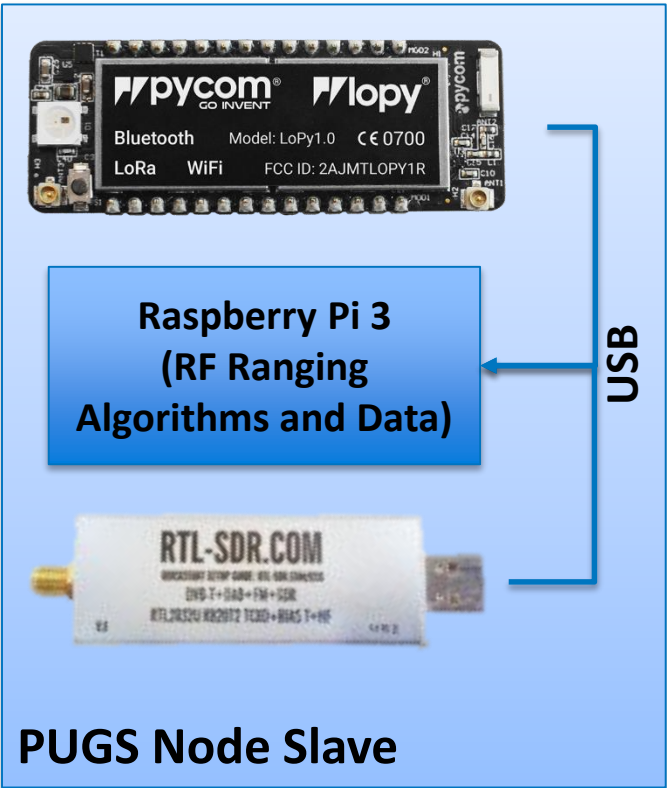


Send Request for Data Capture at Hopped Frequency

Communication Packet from Master

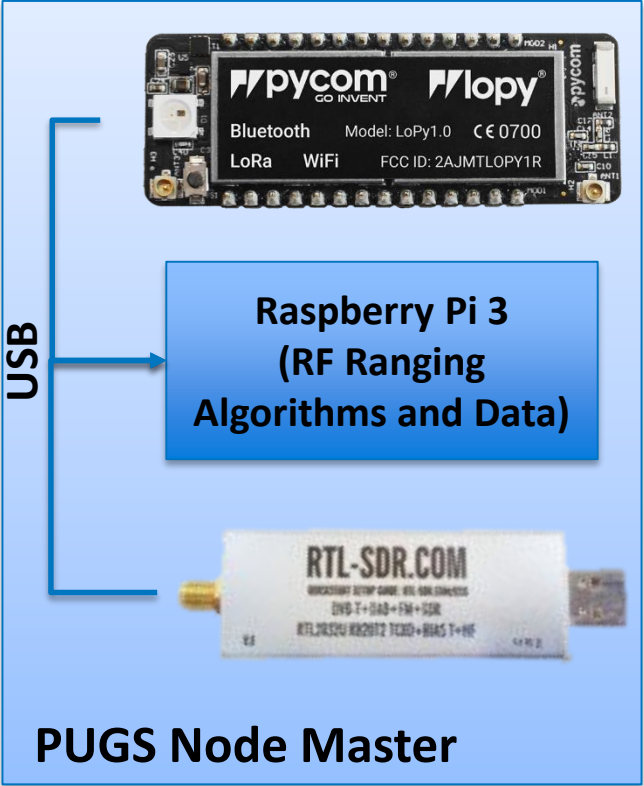
Reply Communication Packet from Slave

Slave



Experimental Operation with PUGS

Master

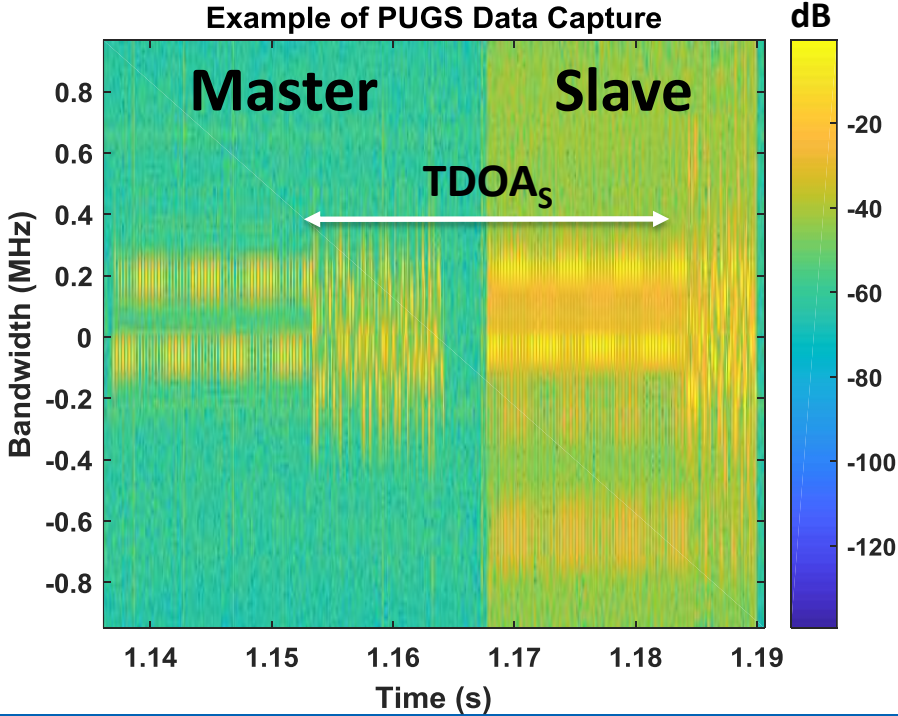
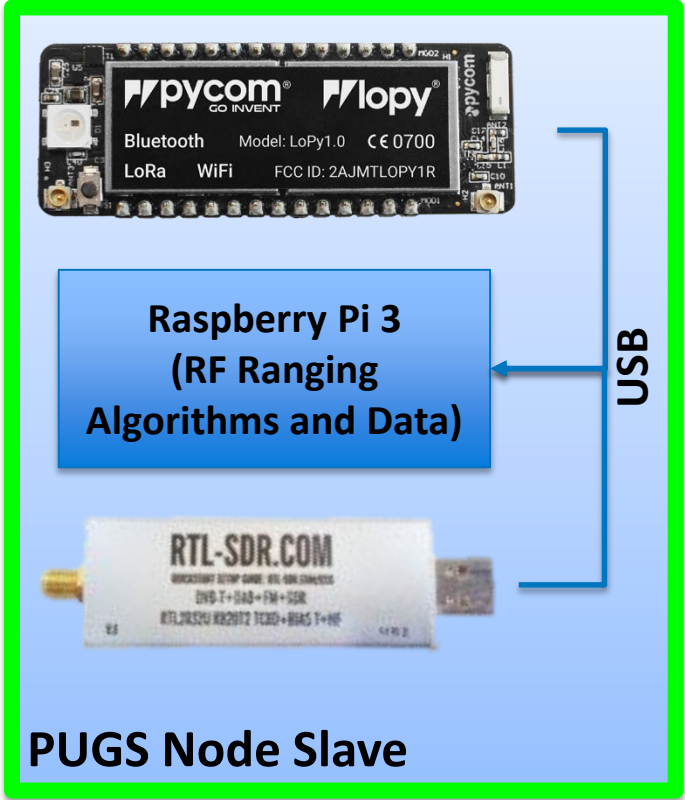


Send Request for Data Capture at Hopped Frequency

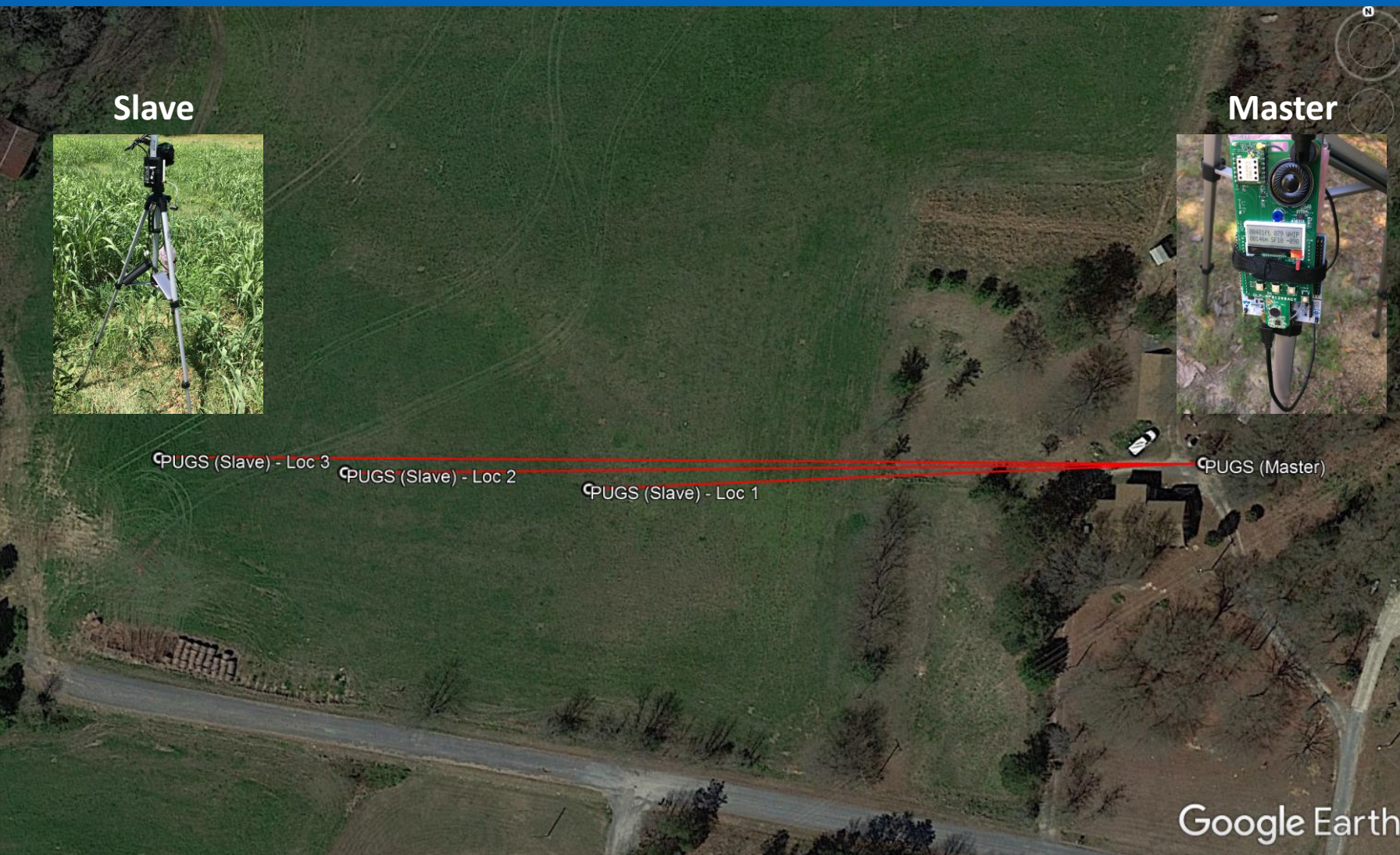
Communication Packet from Master

Reply Communication Packet from Slave

Slave

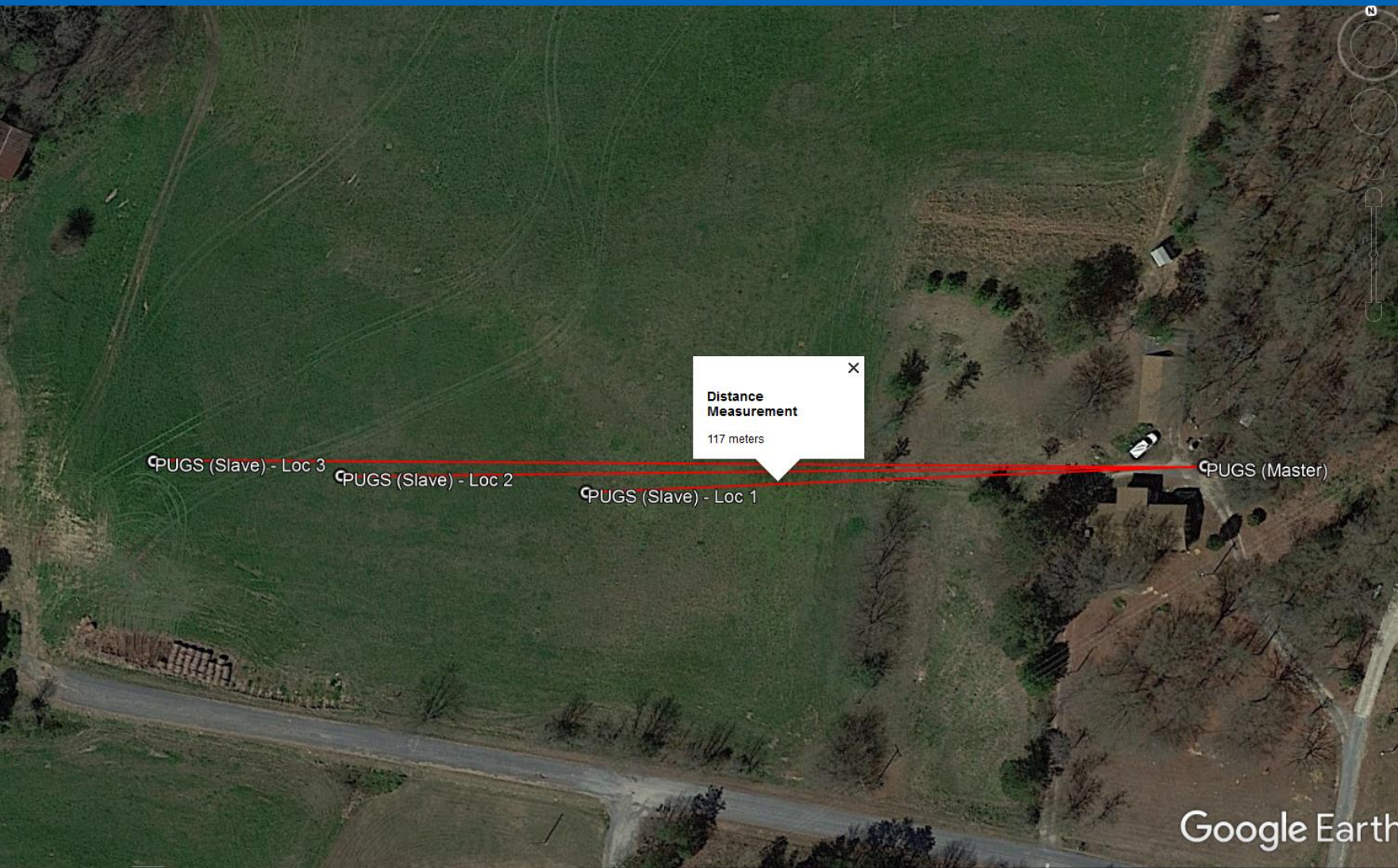


Two-way Ranging Experiments with PUGS



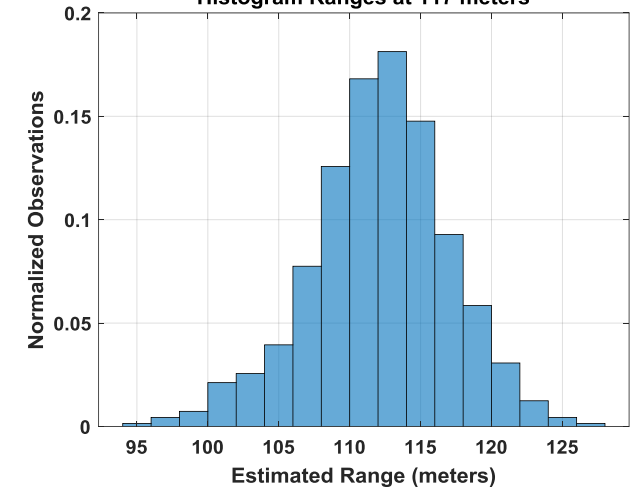
- Leveraged Low SWAP-C 2.4 GHz RF Ranging Transceiver to support PUGS Experimentation
- MicroPython based operation of IoT transceivers provided rapid RF ranging protocol exploration
- Hopped over 26 frequencies in 900 MHz ISM Band
- RTL-SDR data capture at each PUGS for RF ranging algorithm exploration based on post processing analysis
- Transmitter operating level of PUGS at 5 dBm
- RF ranging measurements up to ~200 meters
- GPS measurements collected on each PUGS

Two-way Ranging Experiments with PUGS



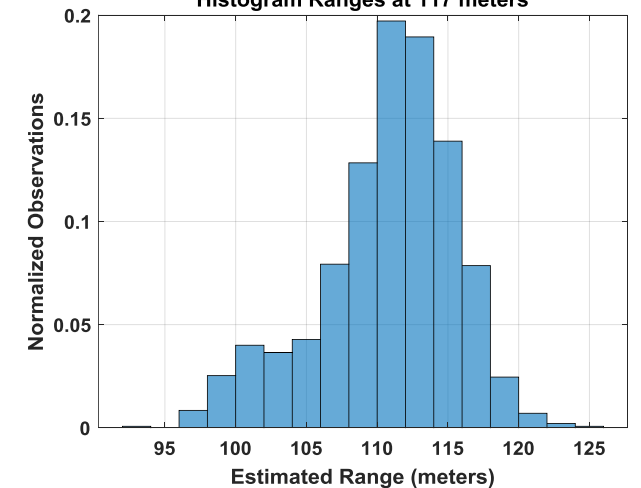
Std = 4.8m Mean = 112m Total Obs = 1368

Histogram Ranges at 117 meters



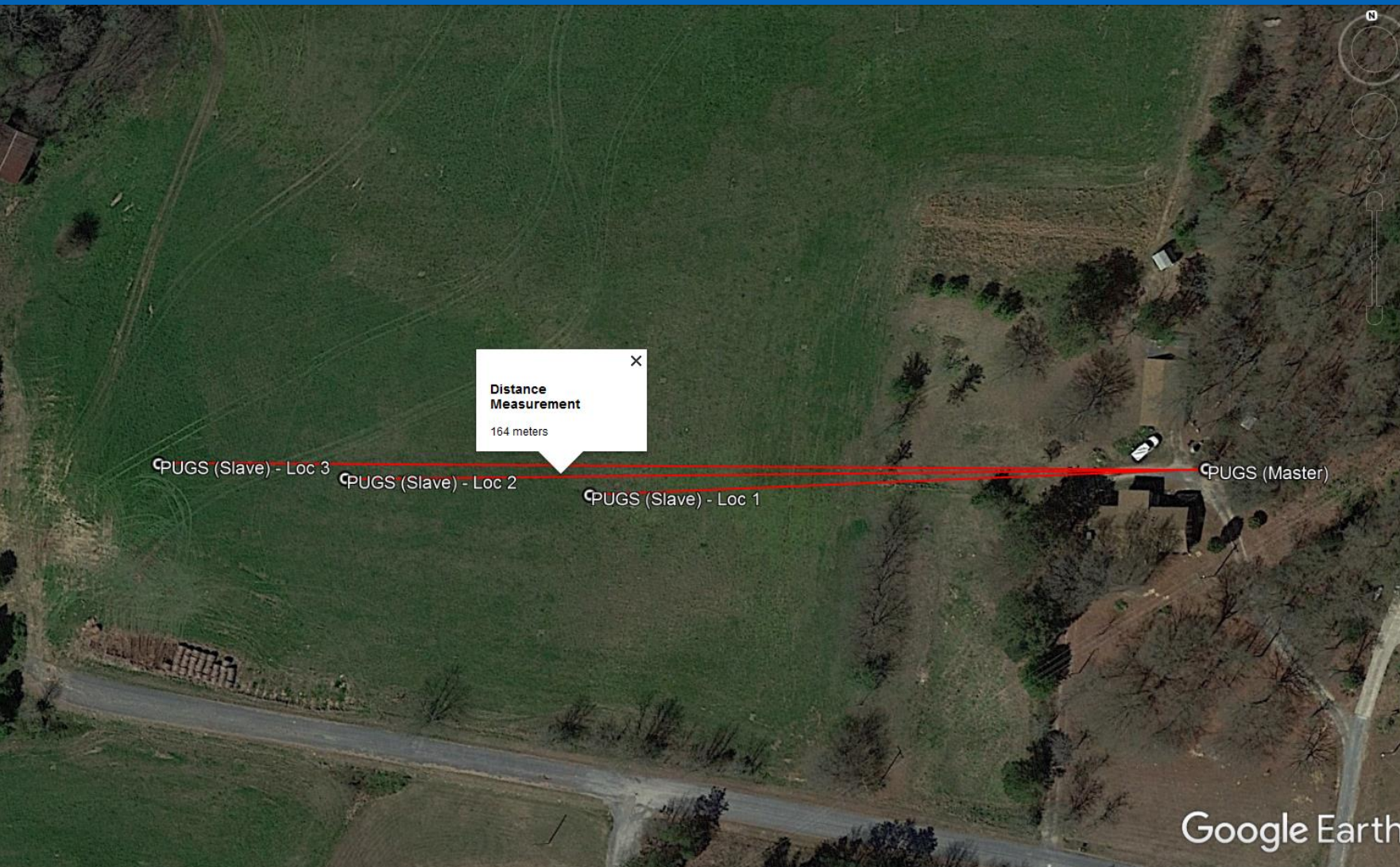
Std = 4.8m Mean = 111m Total Obs = 1425

Histogram Ranges at 117 meters



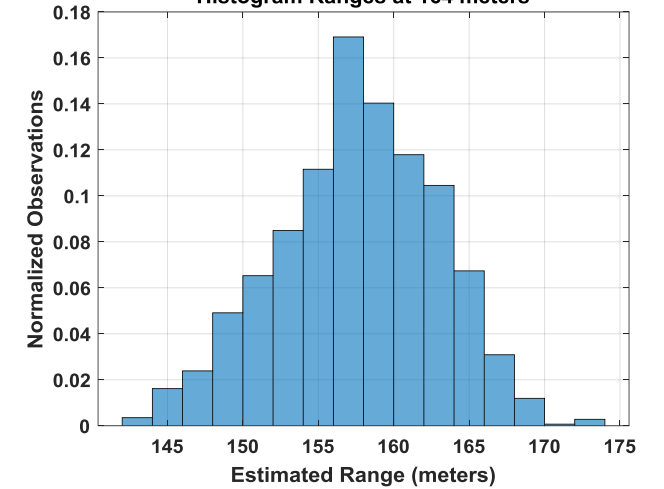
Google Earth

Two-way Ranging Experiments with PUGS



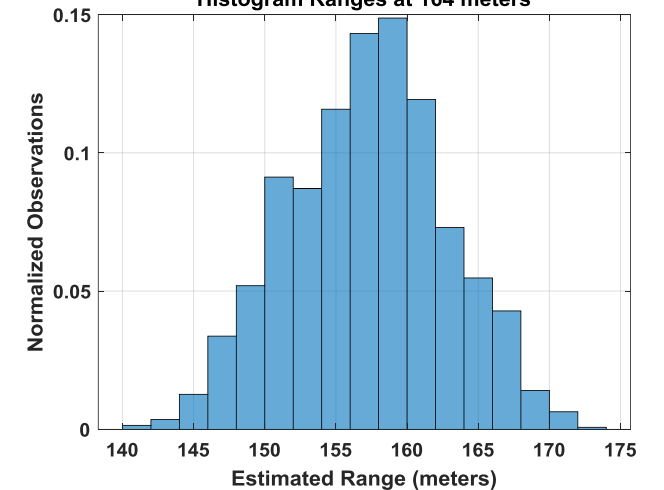
Std = 5.3m Mean = 158m Total Obs = 1425

Histogram Ranges at 164 meters

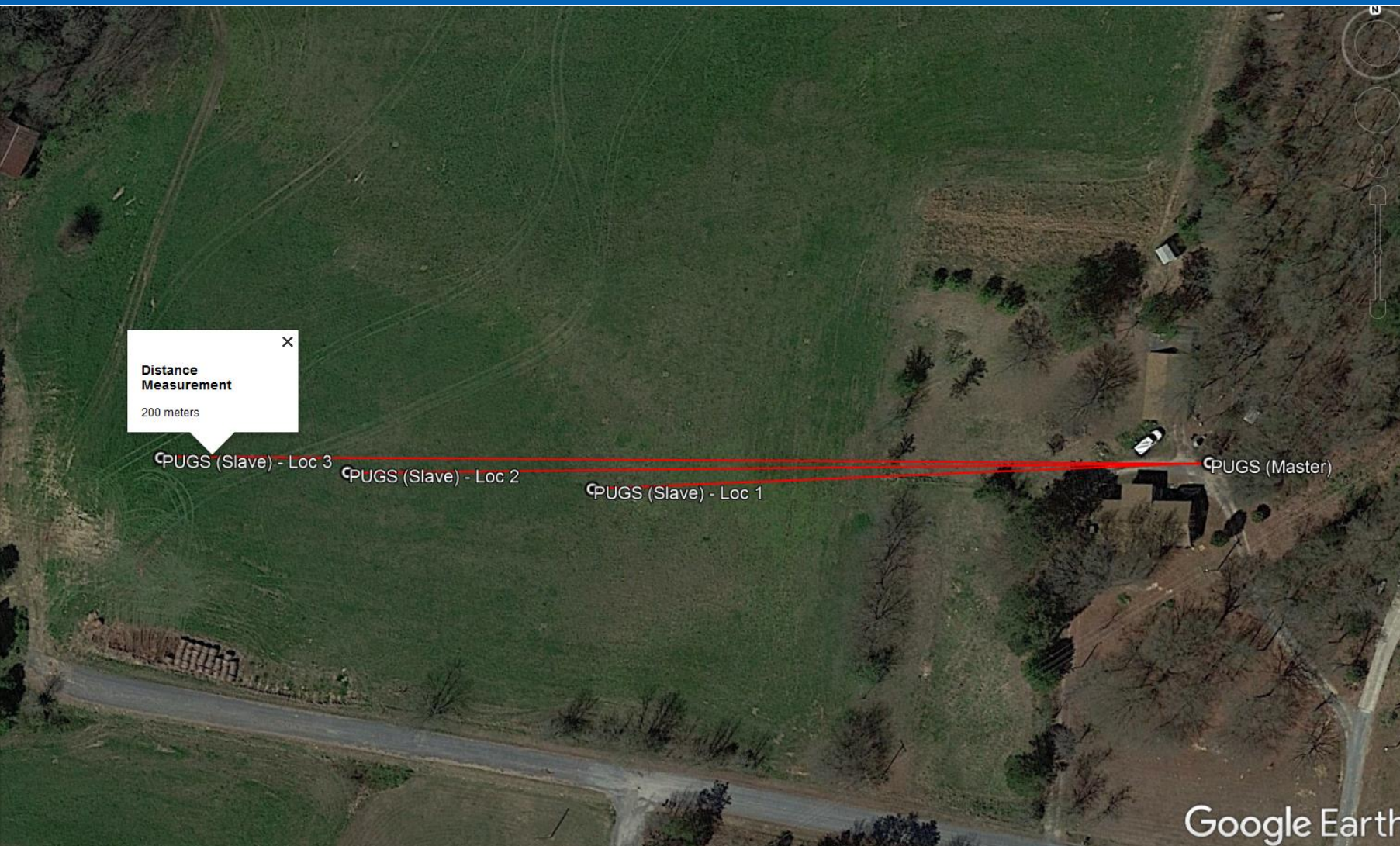


Std = 5.6m Mean = 158m Total Obs = 1425

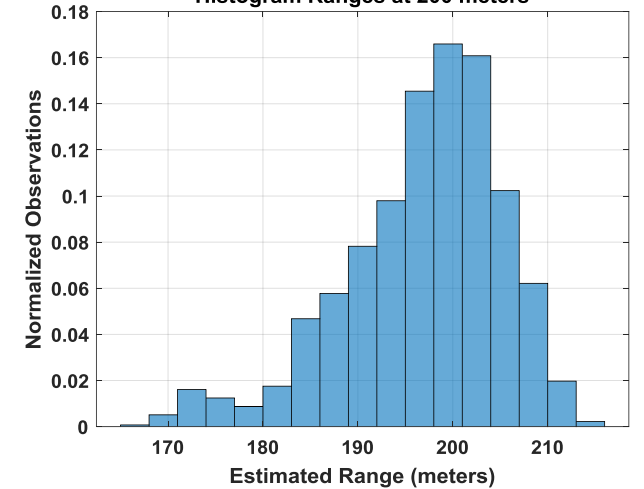
Histogram Ranges at 164 meters



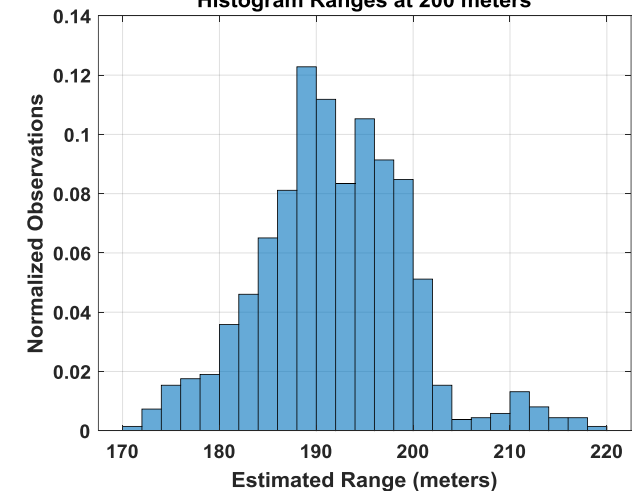
Two-way Ranging Experiments with PUGS



Std = 8.3m Mean = 197m Total Obs = 1368
Histogram Ranges at 200 meters



Std = 7.8m Mean = 192m Total Obs = 1368
Histogram Ranges at 200 meters



Summary and Next Steps with GNU Radio

- LoRa RF Ranging Python Block with PUGS demonstrates the feasibility of < 10 meter level ranging with low SWAP-C COTS IoT transceivers and SDRs without access to RF physical layer measurements
- LoRa RF Ranging Python block provides a great experimental framework for exploring additional PNT research topics with respect to IoT transceivers and low cost SDRs
- Further GNU Radio Python block development is planned based on Angle-of-Arrival algorithms in a distributed PUGS configuration



Questions?



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Ideas to Reality™